# ON THE CORRELATION OF ROTATIONALLY INELASTIC RATES: <br> A SCALING THEORETICAL ANALYSIS 

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#### Abstract

The recently measured rates for the rotationally inelastic process $\left(\mathrm{A}^{1} \mathrm{~S}_{\mathrm{u}}\right) \mathrm{Na}(j)+\mathrm{Xe} \rightarrow\left(\mathrm{A}^{1} \Sigma_{\mathrm{u}}\right) \mathrm{Na}_{2}\left(i^{\prime}\right)+\mathrm{Xe}$ are analyzed and correlated with a scaling theory that explicitly accounts for the adabaticity of the collision. A brief discussion of previous scaling theories (which neglect this effect) is presented.


An a-prioni scaling relationship between rotationally inelastic rates $[1-3]$ has been shown to allow the extraction of state-to-state information from vibrationrotation linewidth data [1]. It is the purpose of this letter to show that such a scaling relationship has an important additional application as a means of data correlation, reduction ans prediction. This method of data analysis has an extremely desirable property: the collisional information is contained in a single column of the physically measurable rate matrix.

Consider the case of rotational relaxation. The standard method of data compaction that has been employed by several investigators [4] involves the fitting of the measured inelastic rates, $k_{j}$, to a function of the so-called natural variables. In rotational relaxation, the transition energy is nearly always used, and a common choice for the function is an exponential $[4,5]$,
$k_{i I}=k_{i I}^{0} B \exp \left(-\theta \mid \epsilon_{i}-\epsilon_{i} 1\right)$.
Here $\epsilon_{i}$ denotes the energy of the $i$ th state, $k_{i j}^{0}$ is a prior (statistical) rate, and the parameters $B$ and $\theta$ are determined by yielding the best fit to a large amount of data. Note that eq. (1) reduces all the unknown rates to knowledge of just two parameters that have no

[^0]simple or direct physical significance.
A general scaling relationship has recently been developed for vibrationally and rotationally inelastic processes and a detailed account will appear elsewhere [6]. For rotational inelasticity in atom-linear molecule collisions, the general expression relating kinetic rates reduces to the simple form

$k_{j j^{\prime}}(T)=\left[j^{\prime}\right] \sum_{L=j-j^{\prime}}^{j+j^{\prime}}[L]\left(\begin{array}{cc}j & j \\ 0 & 0 \\ 0 & 0\end{array}\right)^{2}|A j|^{2} k_{L 0}(T)$,
with the restriction $\epsilon_{j}>\epsilon_{j^{\prime}}$. In the above expression $[l]=2 l+1,(\because)$ is a $3-j$ symbol. and $A_{L}^{j}$ is an adiabaticity factor, which is given in terms of an effective collision length $L_{c}$ as
$A_{L}^{j}=\left[\frac{6+\left[\left(\epsilon_{L}-\epsilon_{L-1}\right) I_{c} / 2 v \hbar\right]^{2}}{6+\left[\left(\epsilon_{j}-\epsilon_{j-1}\right) I_{c} / 2 v \hbar_{1}\right]^{2}}\right]$,
where $v=(8 k T / \mu \pi)^{1 / 2}$ is the average projectile speed. (For homonuclear molecules, $L-1$ and $j-1$ are replaced by $x-2$ and $i-2$ respectively.) Note that the restriction of eq. (2) to downward transitions does not limit its applicability since upward transition rates are related to these by detaled balance.

An understanding of the adiabaticity factor in eqs. (2) and (3) is especially important for the proper analysis of experimental data. Physically, $A_{L}^{j}$ specifically accounts for the finite collision time, $\tau_{c}=l_{c} / v$. For appropriate kinetic energies in systems with a small
collisional reduced mass and/or cases having closely spaced energy levels (e.g., $\mathrm{He}-\mathrm{CO}$ ), $A_{L}^{I}$ is nearly unity and thus can be safely neglected. In the limit that $\mathcal{L}_{L}^{j}=1$ and as $\left(\epsilon_{j}-\epsilon_{j}\right) / k T \rightarrow 0$, eq. (2) reduces to the infinite order sudden (IOS) scaling formula of Goldflam et al. [3]. For cases with larger reduced mass (such as Na*-Xe which is considered later) or at sufficiently high $j$, the adiabaticity factor plays a crucial role in determining the variation of the rates $k_{j j-\perp}$ with $j$ for fixed $A$ In this regard, note that all of the variables except $I_{c}$ in eq. (3) are explicitly given in terms of static properties of the collision system such as the mass and energy level spacing. Since the physical interpretation of $l_{c}$ is defined in terms of the average impact parameter for inclastic collisions, it is often easy to adequately estimate $I_{\text {c }}$. For rotational transitions in neutral atom-molecule collisions, a crude value for $I_{c}$ can be taken as the hard sphere radius. In many applications of eq. (2) - such as when $k_{1.0}$ are known and the other rates are predicted - the estimated $l_{c}$. is quite adequate and yields good results [6]. When aceurate experimental data is availible (especially as a function of initial rotor level), $l_{c}$ no longer need be totally estimated but can he determined more precisely by comparison to the data. We emphasire that $l_{c}$ still must be pitysically reasonable and is thus not a purely adjustable parameter. In essence, the analysis of experimental mesurements can yield both the specific dynamical rates. $k_{\text {I. }}$. and in improved range for the effectise collision length, $I_{c}$. Whth this information available, the rates $k_{j /}$ for all $;$ and $;$ can be generated from (2).

The relationship in eq. ( 2 ) is a specific illustration of a generai scaling formula for non-reactive collisions which is fully discussed elsewhere [6]. For this special atom-linear molecule case. two orher scaling theories [2.3] are available. First. as discussed above. the IOS formula sets $-i_{L}^{I}=1$ and $\left(\epsilon_{i}-\epsilon_{i}\right) i k T=0$ and thus is a durect limiting form of eq. (2). Second. the dynamic coupling theory [2] (DCT) relationship includes the energ: letel spating as in eq. (2) but sets $A_{H}^{j}=1$ and makes an additional assumption about the form of the potential matrix elements. It is not a direct himit of eq. (2) but the DCT sazling expression can be easily modified to incorporate the adiabaticity. The result is

$$
\begin{align*}
& k_{i j}(T)=\frac{[j!l i-i]}{[i]} \frac{N(k T)}{V\left(k T+\epsilon_{j}-\epsilon_{i-j}\right)} \\
& \quad \times 1_{i-i^{\prime}} 1^{2} k_{j-i} 0 \tag{4}
\end{align*}
$$

for $\epsilon_{j}>\epsilon_{j}$ and where $N(E)$ is the number of rotor levels accessible at total energy $E$. There is a difference between eqs. (2) and (4) in that DCT relates each rate $k_{i j}$ only to $k_{1 i-i^{\prime} 10}$, while the relationship in eq- (2) includes all higher order effects as well.

As an example of the utility and power of this data analysis procedure, consider the collision system ( $A^{1} \Sigma_{u}$ ) $\mathrm{Na}_{\underline{2}}^{*}-\mathrm{Xe}$, in which rotational rates have been experimentally determined $[7,8]$ for 6 initial states and a variety of final states at $T \approx 450 \mathrm{~K}$. We choose as input the set $k_{j}{ }^{\prime} 16 \dot{j}^{*}=18,20 . .48$, which are derived from $k_{16 j}$ by detailed balance. Then, if we adopt the relationship embodied in eq. (2), the rates $k_{L 0}$ are obtained as the solution to the linear equations
$k_{\dot{i} 16^{\prime}}(T)=[16] \sum_{i=i=16}^{\vec{j}+16}[L]\left(\begin{array}{cc}i \\ i & 16 \\ 0 & 0\end{array}\right)^{2}\left|A_{L}^{\vec{J}}\right|^{2} k_{L 0}(T)$.
A multistep procedure is used to solve eq. (5): start with $k_{1816}$. truncate the sum over $L$ to only the lowest term and solve for $k_{20}:$ next include $k_{18} 16$ and $k_{2016}$, truncate the sum over $L$ to the two lowest terms and solve for $k_{20}$ and $k_{40}$ : repeat this procedure up till $k_{48} 16$. The systematic inclusion of the higher $\vec{j}$ rates in eq. (5) enables one to determme the convergence of the rates $k_{L 0}$. Following this procedure we fcund that the rates $k_{L 0}$ up to $L=24$ were converged out of the set $k_{20}, \ldots . k_{640}$ using input up to $k_{4816}$. (The higher rates were unconverged but decreasing rapidly in magnitude and thus are relatively unimportant for all $k_{j} j$ with $|j-j| \leqslant 24$.) Note that eq. (5) can be solved for $k_{L 0}$ with any value of $t_{c}$. One method for calculating $I_{c}$ would do a least squares fitting to the data. We have not used this technique but have determined $l_{c}$ by comparison of the scaling predicted and experimental values of $k_{7674}$. This was sufficient for the analysis of the present data. We also mention that with the modified DCT scaling relationship, a simpler andysis is possible: the $k_{L .0}$ 's are obtained by setting $j^{\prime}=16$ in eq. (4).

The above procedure using eq. (5) yields the converged rates shown in table 1 and $I_{c}=7$ bohr. A more precise value for $I_{c}$ is not warranted by the accuracy of the experimental rates, $k_{\vec{j}} 16$ and $k_{7674}$. For instance, we note that the values of $k_{L 0}$ using $l_{c}=5(8.5)$ bohr are almost identical to those in table 1. and that the predicted value of $k_{76} 74$ is only slightly too large (smali). As expected. a moderate variation of $l_{c}$ does not signifi-

Table 1
Rate constants from the deconvolution of experimental data on $\mathrm{Na}_{2}{ }^{\frac{7}{-}-\mathrm{Xe}}$ collistons ${ }^{\text {a }}$ )

| $L$ | $k_{L 0}^{2}$ | $k_{L 0}^{\mathrm{b}}$ |
| :--- | :--- | :--- |
| 2 | $0.7891 \pm 0.0363$ | $0.5479 \pm 0.0123$ |
| 4 | $0.2325 \pm 0.0230$ | $0.1650 \pm 0.0060$ |
| 6 | $0.0937 \pm 0.0237$ | $0.0811 \pm 0.0046$ |
| 8 | $0.0802 \pm 0.0210$ | $0.0558 \pm 0.0035$ |
| 10 | $0.0541 \pm 0.0190$ | $0.0376 \pm 0.0030$ |
| 12 | $0.0351 \pm 0.0175$ | $0.0269 \pm 0.0025$ |
| 14 | $0.0367 \pm 0.0162$ | $0.0219 \pm 00021$ |
| 16 | $00222 \pm 0.0150$ | $0.0158 \pm 0.0018$ |
| 18 | $0.0245 \pm 0.0140$ | $0.0136=0.0018$ |
| 20 | $0.0222 \pm 0.0130$ | $0.0107 \pm 0.0016$ |
| 22 | $0.0192 \pm 00121$ | $0.0081 \pm 0.0014$ |
| 24 | $0.0125 \pm 0.0112$ | $0.0058 \pm 0.0014$ |

a) The rates $k_{L o}$ obtained from the scalus relationship of eq(5) and the modified DCT ${ }^{\text {b }}$ both using $I_{c}=7$ bohr are presented here. The temperature is 450 K , and the units of the rates are $10^{-10} \mathrm{~cm}^{3} \mathrm{~s}^{-1}$. The stated uncertainties are due solely to esperimental error. Note that the rates in column a using eq- (5) are converged with respect to adding higher input rates $k_{j} 16$ -
cantly effect the scaling theoretical analysis. However, the neglect of $A_{L}^{j}$ (i.e., $I_{c}=0$ ) as in the IOS scaling relationship, will yield rates in upper $j$ levels that are significantly too large. In the analogous DCT procedure the value $I_{c}=7$ bohr also reproduced the data accurately. The resulting rates are shown in table 1.

An interesting point is that the matrix of rates $k_{H^{\prime}}$
with $j \neq 0, I^{\prime} \neq 0$ predicted by either eq- (2) with $k_{L 0}$ from the first column of tuble 1 or by eq. (4) and the $k_{L 0}$ 's from the second column are in very good agreement. However, the differences between $k_{20}$ and $k_{40}$ derived from the two methods serve to stress the difference in the models as discussed above. We have used a gaussian form for the experimental input rate error to determine the uncertainties in the deconvoluted rates. The non-overlapping of some of the error bars in columns I and II is due to the complete neglect of any model errors. In fact, both scaling relationships are unlikely to be consistently more accurate than $\pm 10 \%$ - to judge from previous work $[2,6]$. As a consequence. the two columns are actually in reasonably good agreement, especially concerning the propensity for multiple quantum transitions.

Due to the easy generalization of eq. (2) to more complicated systems [6], the followng discussion is based upon the results using this equation. Similar comments would hold for the results of eq. (4). Using the $k_{L 0}$ rates and $l_{c}$, any individual rate $k_{j j^{\prime}}$, including those not experimentally measured can be calculited via eq(2). These are depicted in fig. 1 for sample cases, along wth the measured rates. It can be seen that the agreement between the predicted and measured rates is excellent. Sinular agreement is found for all the rates in ref. $[7]$. Since the values of $k_{54 j}$, with $A_{L}^{i}=1$ would be nearly equal to $k_{16 j^{\prime}}$, it is clear that the adiabaticityfactor is quite important in this heavy system and that the analysis based upon eq. (2) is capable of correlating


Fig. 1. Scaling predicted and experimental rates: The rates $k_{1616 * \Delta}{ }^{(0)}$ are used to determine the $k_{L_{0}}$ in eq. (5). The sealing predicted rates $k_{54 j^{\prime}}(4)$ and $k_{1616-\Delta}(*)$ agree with the corresponding experimental values $k_{54 j^{\prime}(+)}$ and $k_{1616-\Delta}(-)$ within the experimental uncertainty.
and compacting the data, and predicting the rates. Thus, a purely parametrical fitting of the experimental results is unnecessary ${ }^{\dot{1}}$. We mention that the adiabaticity factor should be less important for the $\mathrm{Na}_{2}^{*}-\mathrm{He}$ system and consequently the rates in the upper levels should not decrease as rapidly as those in $\mathrm{Na}_{2}^{*}-\mathrm{Xe}$ collisions. An experimental verification of this prediction would be interesting.

The $\mathrm{Na}_{2}^{*}-\mathrm{Xe}$ example illustrates the value of the present procedure as a means of data-compaction, since only the $k_{L 0}$ rates and $I_{c}$ are needed to obtain all other rates. At the same time, such a relationship must not be viewed simply as fitting procedure, since the rates $K_{L 0}$ and effective collision length $I_{c}$ have explicit dynamical meaning, and they are obtained by the deconvolution. In this regard, the predictive and non-adjustable nature of eq. (2) allows an in-depth analysis of relaxation effects. In addition, an unsuccessful attempt at a deconvolution would imply that unusual dynamical effects are occurring, and thus would

This point is important for tine interpretation of the data. For instance, it has recently been concluded that a propensity for $m_{j}=m_{j}$ exists in the $\mathrm{Na}_{2} \frac{1}{2}-$ Xe system [7,9]. Since eq. (2) includes all reorientations, the piesent analysis shows this conclusion to be an artifact of the assumed functional form and the chosen prior. This is an inherent weakness of any parametrization procedure. Explicitly, the basic dynamical quantities $k_{\text {Lo }}$ can be fitted equally well by either of the forms $k_{L 0}=B[L(L+1)]^{5}$ or $k_{L 0}=\left(B^{*} /[L]\right)[L(L+1)]^{s^{\prime}}$. Since the first function assumes a statistical prior, and the second assumes no reorientation, no unambiguous information about reorientations can be obtained with either of the above forms.
point out a system for further study $\ddagger \dagger$. By contrast, a poor fit to the data by an arbitrarily assumed functional form merely warrants a different functional form - no more and no less.

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ii See, for example, the deconvolution of linew idth data for near-homonuclear molecules as presented in ref. [1].

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